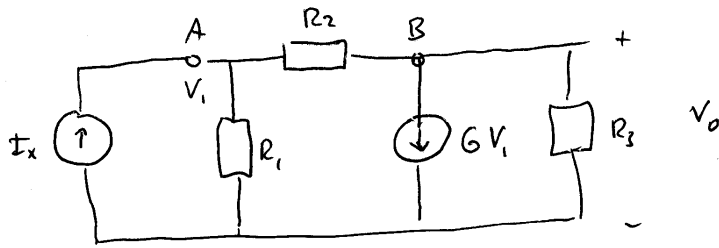


1)



$$G_i = 1/R_i$$

A: $I_x = G_1 V_1 + G_2 (V_1 - V_0)$

$$I_x = (G_1 + G_2) V_1 - G_2 V_0 \quad \text{I}$$

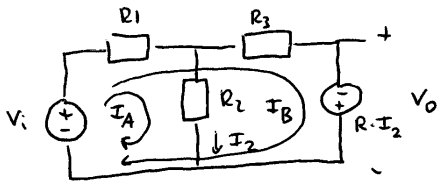
B: $G_2 (V_1 - V_0) = G V_1 + G_3 V_0$

$$0 = (G - G_2) V_1 + (G_3 + G_2) V_0 \quad \text{II}$$

Cramer:

$$V_{out} = \frac{\begin{vmatrix} G_1 + G_2 & I_x \\ G - G_2 & 0 \end{vmatrix}}{\begin{vmatrix} G_1 + G_2 & -G_2 \\ G - G_2 & G_2 + G_3 \end{vmatrix}} = I_x \frac{G_2 - G}{G_1 G_2 + G_1 G_3 + G_2 G_3 + G G_2}$$

2)



$$I_A = I_2$$

A: $R_1 I_A + R_2 I_A + R_3 I_B = V_i$

$$V_i = (R_1 + R_2) I_A + R_3 I_B \quad \text{I}$$

B: $(R_1 + R_2) I_A + R_1 I_B = V_i$

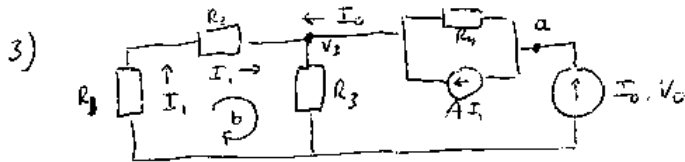
$$I_A R_1 + I_B R_1 + I_B R_3 - I_A R = V_i$$

$$V_i = I_A (R_1 - R) + (R_1 + R_3) I_B \quad \text{II}$$

Cramer:

$$I_2 = I_A = \frac{\begin{vmatrix} V_i & R_1 \\ V_i & R_1 + R_3 \end{vmatrix}}{\begin{vmatrix} R_1 + R_2 & R_1 \\ R_1 - R & R_1 + R_3 \end{vmatrix}} = V_i \frac{R_3}{R_1 R_3 + R_2 R_3 + R_1 R_2 + R_1 R}$$

$$V_0 = -R I_2 = \frac{-R R_3}{R_1 R_3 + R_2 R_3 + R_1 R_2 + R_1 R} V_i$$



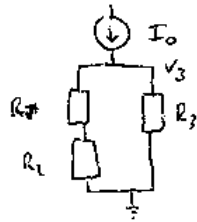
node a:
$$\dot{I}_0 = A I_1 + \frac{(V_0 - V_3)}{R_4} \quad \text{(I)}$$

malha b:
$$I_1 (R_1 + R_2) + R_3 (I_1 + I_0) = 0$$

$$I_1 (R_1 + R_2 + R_3) = -R_3 I_0$$

$$I_1 = -R_3 I_0 / (R_1 + R_2 + R_3) \quad \text{(II)}$$

ponto V_3 :



$$V_3 = I_0 (R_3 // (R_1 + R_2))$$

$$= I_0 \frac{R_1 R_3 + R_2 R_3}{R_1 + R_2 + R_3} \quad \text{(III)}$$

(II) e (III) em (I):

$$I_0 = \frac{V_0}{I_0} = \frac{(R_1 + R_2) R_3 + A R_3 R_4 + R_4 (R_1 + R_2 + R_3)}{(R_1 + R_2 + R_3)}$$

4)
$$V_0 = A (V_b - V_a)$$

$$V_b = \frac{R_4}{R_3 + R_4} V_2$$

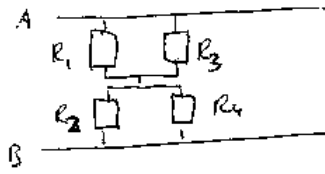
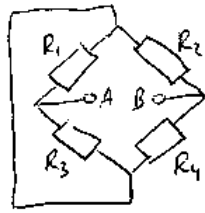
$$V_a = \frac{R_2}{R_1 + R_2} V_1 + \frac{R_1}{R_1 + R_2} V_0$$

$$V_0 = A \left(\frac{R_4}{R_3 + R_4} V_2 - \frac{R_2}{R_1 + R_2} V_1 - \frac{R_1}{R_1 + R_2} V_0 \right)$$

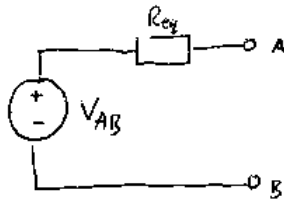
$$V_0 = \frac{A}{1 + A \frac{R_1}{R_1 + R_2}} \left(\frac{R_4}{R_3 + R_4} V_2 - \frac{R_2}{R_1 + R_2} V_1 \right)$$

5) curto-circuito a fonte de tensão

ELI (3)



$$R_{eq} = R_1 // R_3 + R_2 // R_4$$

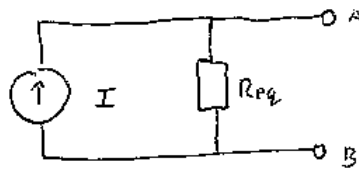


← Thévenin

$$V_A = \frac{R_3}{R_1 + R_3} V \quad V_B = \frac{R_4}{R_2 + R_4} V$$

$$V_{AB} = \left(\frac{R_3}{R_1 + R_3} - \frac{R_4}{R_2 + R_4} \right) V$$

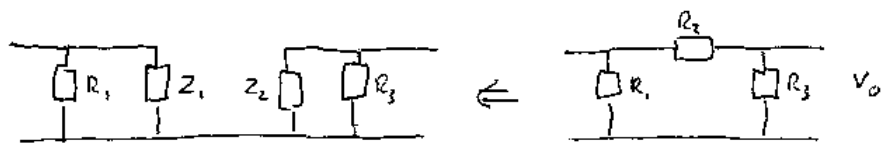
6)



← Norton

$$I = \frac{V_{AB}}{R_{eq}}$$

7)



$$Z = R_2, \quad V_o = -G V_1 R_3 \quad (R_2 \gg R_3)$$

$$k = -G R_3 \quad (V_o / V_1)$$

$$Z_1 = \frac{Z}{1-k} = \frac{R_2}{1+G R_3}, \quad Z_2 = \frac{Zk}{k-1} = \frac{G R_2 R_3}{1+G R_3} \quad (\approx R_2)$$

$G R_3 \gg 1$